

4.1.1 $\vec{\theta} = \sin a\theta = f(\theta)$

to uniquely define a vector field on the circle,
we need $f(\theta + 2\pi) = f(\theta)$

ie. $\sin a(\theta + 2\pi) = \sin a\theta$

use angle addition formula

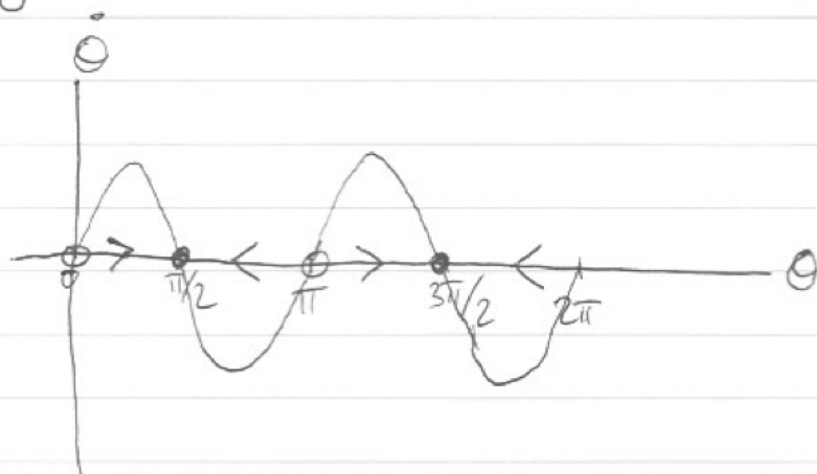
$$\begin{aligned}\sin a(\theta + 2\pi) &= \sin(a\theta + 2\pi a) \\ &= \sin a\theta \cos 2\pi a + \cos a\theta \sin 2\pi a\end{aligned}$$

so require $\cos 2\pi a = 1, \sin 2\pi a = 0$

$$\Rightarrow 2\pi a = 2\pi n \quad n \text{ is an integer}$$

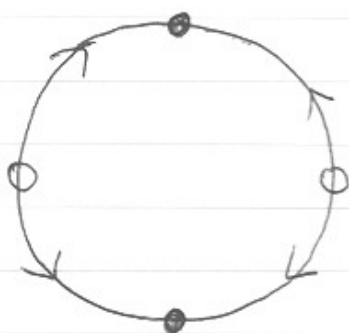
hence, a must be an integer.

4.1.3 $\vec{\theta} = \sin 2\theta$

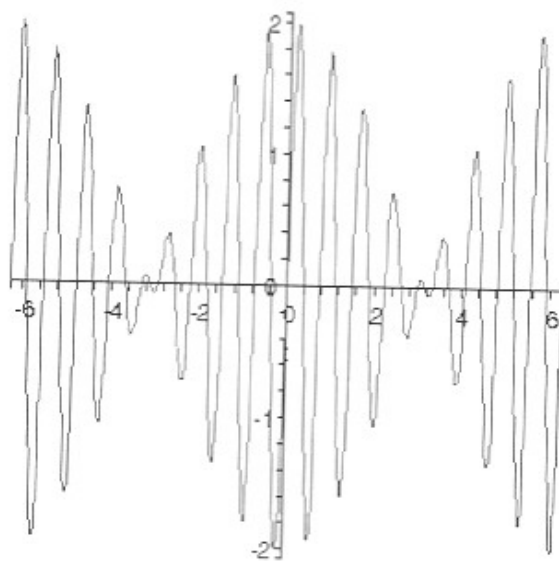


$\theta = 0, \pi$ are unstable fixed points
 $\theta = \pi/2, 3\pi/2$ are stable fixed points

phase
portrait
on
circle



4.2.2



a) $\rightarrow$ read off the period from the graph.



b) use $\sin \alpha + \sin \beta$

$$= 2 \sin \frac{1}{2}(\alpha + \beta) \cos \frac{1}{2}(\alpha - \beta)$$

$$x(t) = \sin 8t + \sin 9t$$

$$= 2 \sin \frac{17}{2}t \cos \frac{1}{2}t$$

$$(NB \cos \frac{1}{2}t = \cos t)$$

rapid oscillations

amplitude modulation.

one period of the amplitude modulation sees $\cos \frac{1}{2}t$ rise from zero to one and back again. see graph in (a)
or goes from 1 to 0 and back again
→ this occurs as $\frac{1}{2}t$ increases from 0 to π

$\Rightarrow t$ goes from 0 to 2π
so period 2π

4.2.3 It's the two joggers example.

Minute hand has period 1 hr, hour hand has period 12 hours. So, from the formula in the notes,

$$T = (1/T_1 - 1/T_2)^{-1} = 12/11 \text{ hours.}$$

I think it would be better to spell out the detail (which isn't much more to do)...

$$\dot{\theta}_1 = \omega_1 = \frac{2\pi}{1} = 2\pi \Rightarrow \theta_1 = 2\pi t$$

$$\dot{\theta}_2 = \omega_2 = \frac{2\pi}{12} = \pi/6 \Rightarrow \theta_2 = \pi t/6$$

$$\begin{aligned}\theta_1 &= \theta_2 + 2\pi \Rightarrow 2\pi t = \frac{\pi t}{6} + 2\pi \\ &\Rightarrow 11\pi t/6 = 2\pi\end{aligned}$$

again giving 12/11 hours.

Intuitive methods

First method: We know that the hands are aligned at noon and again at midnight, a twelve hour period during which they cross 11 times. (At 1:something, 2:something, 3:something, ... 10:something, 11:something—except that the 11:something one must be at midnight). So there are 12/11 hours between crossings.

Second method: Imagine the minute hand trying to catch up to the hour hand after the first hour has been completed. We keep track of a sequence of steps in which the minute hand moves to the previous location of the hour hand.

Note: minute hand completes a revolution in 1 hour, hour hand completes a revolution in 12 hours, so is rotating at 1/12 revolution per hour.

After 1 hour, minute hand has completed 1 revolution, hour hand has completed 1/12 of a revolution. Minute hand needs to catch up 1/12 revolution.

Minute hand takes 1/12 hour to make 1/12 revolution. But in this time, hour hand has moved $(1/12)^2$ revolutions beyond its previous location.

Minute hand takes $(1/12)^2$ hours to move to previous location of hour hand. But in this time, hour hand has moved $(1/12)^3$ revolutions ahead.

Minute hand takes $(1/12)^3$ hours to move to this location, but the hour hand is then $(1/12)^4$ ahead, and so on...

Notice that the two locations converge as the number of steps goes to infinity.

The total time taken for these steps is

$$1 + \frac{1}{12} + \left(\frac{1}{12}\right)^2 + \left(\frac{1}{12}\right)^3 + \dots = \frac{1}{1 - \frac{1}{12}} = \frac{12}{11} \text{ hours}$$

(c.f. Zeno's paradox of Achilles and the tortoise)

alternatively

~~or~~

$$\dot{\theta}_1 = \omega_1 = 2\pi/1 = 2\pi$$

$$\theta_1 = 2\pi t$$

$$\dot{\theta}_2 = \omega_2 = 2\pi/12 = \pi/6$$

$$\theta_2 = \frac{\pi}{6}t$$

$$\theta_1 = \theta_2 + 2\pi \Rightarrow 2\pi t = \frac{\pi}{6}t + 2\pi$$

$$\Rightarrow \frac{11\pi}{6}t = 2\pi$$

$$\Rightarrow t = \frac{12}{11} \text{ hours.}$$

4.3.3 $\dot{\theta} = p \sin \theta - \sin 2\theta$

$$= p \sin \theta - 2 \sin \theta \cos \theta$$

$$= \sin \theta (p - 2 \cos \theta)$$

$$\dot{\theta} = 0 \Rightarrow \sin \theta = 0 \Rightarrow \theta = 0 \text{ or } \pi$$

or $p = 2 \cos \theta$

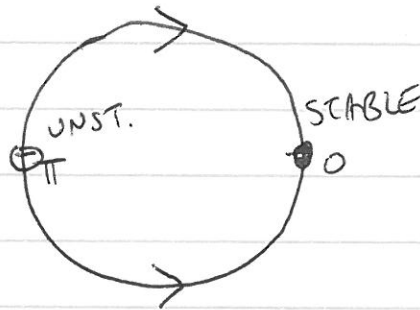
this only has solutions if $-2 \leq p \leq 2$

2 equilibria if $|p| \geq 2$
 4 equilibria if $|p| < 2$

~~When $p = \pm 2$, the solutions of $p = 2 \cos \theta$ are also $\theta = 0$ and π~~

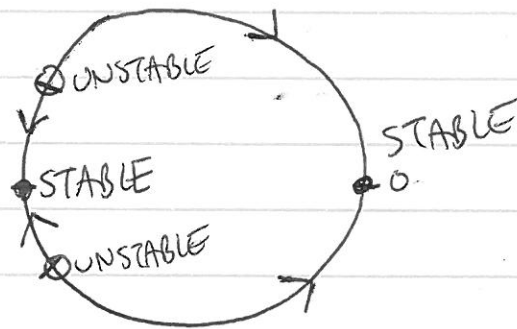
when $p = 2$, the solution of $p = 2 \cos \theta$ is $\theta = 0$
 when $p = -2$, the solution is $\theta = \pi$

$p < -2$ ($p - 2\cos\theta < 0$ for all θ)
 (directions of arrows) depends on sign of $\dot{\theta}$



sign of $\dot{\theta}$
 $\downarrow$
 < 0 for θ between 0 and π ,
 > 0 for θ between π and 2π

$-2 < p < -2$

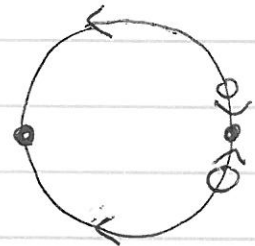
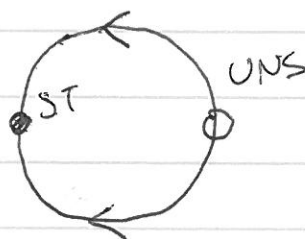


notice: when p is close to -2 , both solutions of $p = 2\cos\theta$ are close to $\theta = \pi$

when $p = 0$, the solutions of $p = 2\cos\theta$ are $\theta = \pi/2, 3\pi/2$

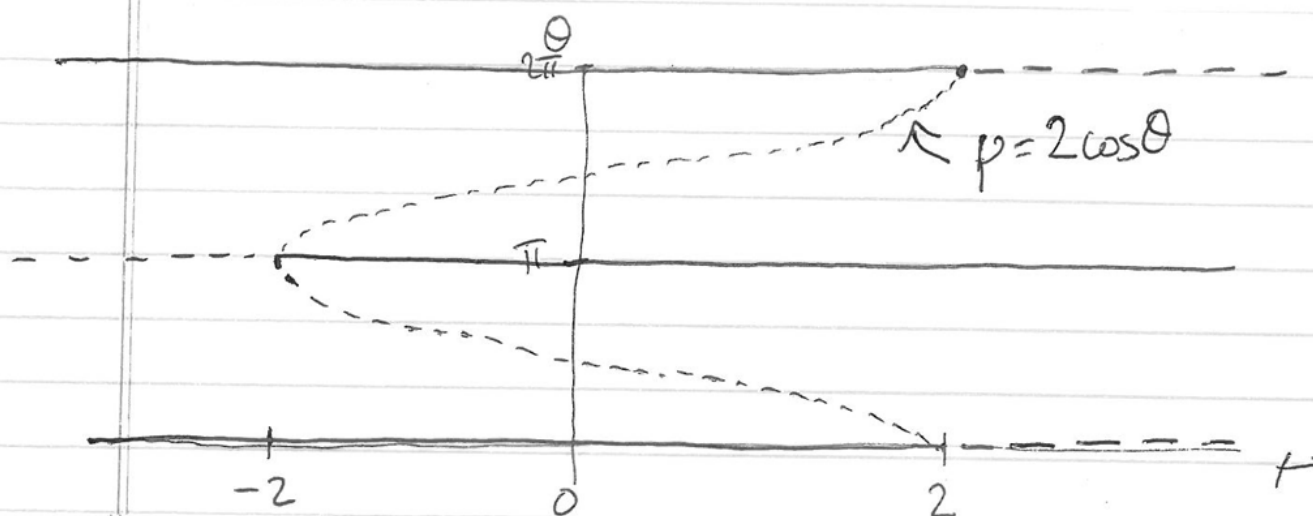
as p approaches 2 we have

$p > 2$



These are pitchfork bifurcations. at $\mu = +2$, $\mu = -2$.

Both are subcritical.



The pitchfork at $\mu = 2$ is easier to see when we remember that 0 and 2π are the same point - we could wrap up the θ direction into a circle.